

Experimental Study on the Configuration Hydrodynamics of Trimaran Ships

Jingbei Jia¹ and Zhi Zong^{2,3}

Received: 07 May 2022 / Accepted: 18 June 2022
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Abstract

This paper presents experimental results on configuration hydrodynamics. Three models are used in the model tests, which are typical of hard, round, and soft chines. Although specific values are different, the influence patterns are similar in the three ship models. A set of different outrigger positions is investigated in calm water and regular waves. A variety of interesting phenomena are observed, among which the splash resistance is the dominant component for a trimaran at high speeds (with Froude number $Fr > 0.6$). If two small outriggers are placed inside Kelvin's wave systems of the main hull, a strong splash appears, resulting in a significant resistance increase. Moreover, short and long waves cannot be neglected, for they may excite the motions of much smaller outriggers. This condition leads to non-vanishing heaving at high-frequency and non-normalized pitches at low frequencies. Based on the tests, three spectra of optimum configurations for resistance, longitudinal motions, and transverse motions are presented. These results reveal the optimum configurations of a trimaran hull in terms of hydrodynamic performance, thus providing a very powerful tool for optimum design of trimaran ships.

Keywords Trimaran ship; Configuration; Hydrodynamics; Splash resistance; Spectra of optimum configurations

1 Introduction

A trimaran comprises a long main hull with two small outriggers (side hulls) on both sides attached to the main hull by lateral beam. Although trimarans had been used by Polyne-

sians long ago, the first large-size trimaran ship had not been conceptualized until the 1990s by researchers at University College London (UCL) (Andrews and Zhang 1995). The Royal Navy was soon ready to build a trimaran demonstrator ship RV Triton (Naval Technology 2001), which was 90 m long, 22 m wide, and 20 kn fast. This was soon overtaken in 2000 by the Austal Aluminum trimaran Benchijigua Express (Ship Technology 2006), which was 102 m long and 40 kn fast. Trimaran hulls may achieve high speeds beyond our previous expectations. Thus, research interests in trimaran ships have greatly intensified in recent years.

Although the displacements of side hulls are small compared with those of the main hull, their longitudinal and lateral positions exhibit important influences on the behaviors of resistance (Ackers et al. 1997) and motions of trimaran hulls (Hebblewhite et al. 2007; Khoob et al. 2021). In fact, UCL researchers already realized the strong interaction among hulls of a trimaran ship as early as in the 1990s (Andrews and Zhang 1995). This is particularly true at high speeds. The challenge is that such influences are complicated, owing to their case dependency (Dogrul and Yildiz 2022; Wang et al. 2009; Zhou et al. 2015; Xu and Zhang 2011). The best position for one specific speed may turn out to be a very bad one for another speed (Wang et al. 2009; Zhou et al. 2015). This phenomenon has been observed in experiment tests (Khoob et al. 2021; Dogrul and

Article Highlights

- A series of experimental tests on different arrangements of main and side hulls show that positions of side hulls relative to the main hull exhibit significant influences on hydrodynamic performance of trimaran ships.
- The optimum configurations at different speeds in calm water and waves are presented, which indicate that forward trimaran performs better at high speeds and backward trimaran performs better at low speeds.
- Experimental results reveal the existence of splash resistance at high speeds (Froude number greater than 0.6).

✉ Zhi Zong
zongzhi@dlut.edu.cn

¹ School of Navigation and Naval Architecture, Dalian Ocean University, Dalian 16023, China

² School of Naval Architecture Engineering, Dalian University of Technology, Dalian 116024, China

³ State Key Laboratory of Structural Analysis for Industrial Equipment, Dalian 116024, China

Yildiz 2022) and subsequent numerical studies (Poundra et al. 2017; Yildiz et al. 2020; Liu et al. 2021). The strong interference between the main and side hulls results in the complexity of trimaran hull configuration. Therefore, it is necessary to optimize configurations on a case-by-case basis (Poundra et al. 2017; Yildiz et al. 2020). Accordingly, recent years have witnessed increasing research interest in the configuration optimization of trimaran ships (Liu et al. 2021; Wang et al. 2021; Lv et al. 2022).

The above-mentioned research leads us to the conclusion that the configuration of the three hulls has significant influences on resistance and ship motions in waves. Hence, it is important to clarify the influence patterns for the different configurations of trimaran hulls. Moreover, a universal optimum position of side hulls for all speeds does not exist (Zhou et al. 2015; Liu et al. 2021; Wang et al. 2021).

Therefore, the problem to be solved in this study is to determine the spectrum of optimum configurations for trimaran ships based on the test results of three models. To do so, a series of experimental tests were conducted, which results are reported in this paper.

2 Model experiments

2.1 Test models

The body plan of the model trimaran, which is denoted as Model A, is shown in Figure 1, and the main particulars are given in Table 1.

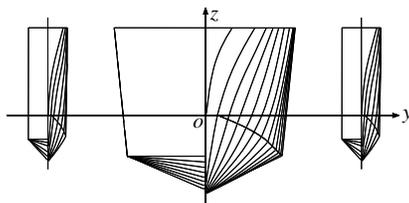


Figure 1 Body plan of Model A

Table 1 Main particulars of Model A

Items	Main hull	Side hulls
Length of waterline (m)	4.000	1.000
Breadth of waterline (m)	0.358	0.085
Draft (m)	0.170	0.100
Displacement (m ³)	0.129	0.004 5
Wetted Surface (m ²)	1.899	0.201
Block coefficient	0.530	0.524
Prismatic coefficient	0.769	0.746

The layout of the hulls is shown in Figure 2. The origin of the coordinates is the intersection of the central longitudinal

profile, midship section, and designed waterline. The lengths of the main hull and side hull are denoted as L_m and L_s , respectively. Similarly, the breaths are denoted as B_m and B_s , respectively. Two key variables, a and b , are introduced to denote the longitudinal and transverse positions of the side hulls, respectively. $a > 0$ implies that the midship section of the side hull is in front of the main hull. The variable b is the transverse distance between the central longitudinal profiles of the main hull and side hulls. The value of b is always positive. A series of configurations are designed, which are shown in Table 2. The configurations that the two side hulls placed at both sides of the bow, midship, and stern of the main hull are denoted as the forward trimaran, middle trimaran, and aft-ward trimaran, respectively.

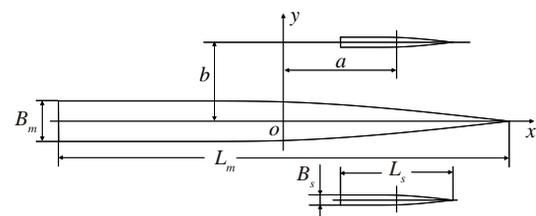


Figure 2 Trimaran configuration

Table 2 Configurations of trimaran Model A

No.	a/L_m	b/B_m	Layout
①	-0.325	1.955	
②	-0.250	1.955	
③	-0.175	1.955	
④	0.0	1.955	
⑤	0.250	1.955	
⑥	-0.175	1.117	
⑦	-0.325	1.117	

2.2 Experimental setup

The experiments were conducted in the towing tank, Dalian University of Technology, an ITTC member. The tank is 160 m long, 7 m wide, and 4 m deep, with wave dampers on the side wall. There is a wave generator at one end of the tank, which can make regular and irregular waves with a maximum wave height of 0.4 m, as shown in Figure 3.

The model trimaran was attached to the carriage, whose maximum speed is 8 m/s. Resistance and motion responses (heaving, pitch, and roll) were measured using the resistance sensor, heaving sensor, and gyroscope, as shown in Figure 4. The picture of the model tests for Model A in the towing tank is shown in Figure 5.

A series of experiments were conducted for all the configurations, including resistance tests in calm water and regular waves and heave, roll, and pitch tests in regular waves.

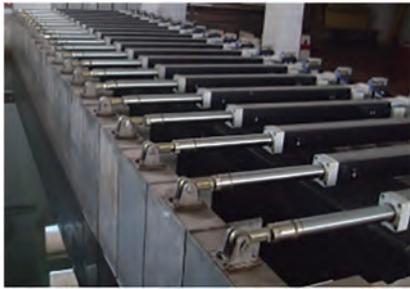


Figure 3 Wave generator composed of 20 small plates



Figure 5 Model tests for Model A in the towing tank



(a) Resistance sensor



(b) Heaving sensor



(c) Gyroscope for pitch and roll

Figure 4 Apparatus used for Model A

3 Experimental results

The results obtained from the experiments were plotted in a series of curves to analyze the influence of the configuration on the trimaran hydrodynamics.

3.1 Resistance in calm water

The resistance measured in calm water tests is the total resistance. The time history of the total resistance of a typical configuration at $Fr = 0.857$ is shown in Figure 6. Small oscillations in the curve can be observed due to the strong interference at the high speed.

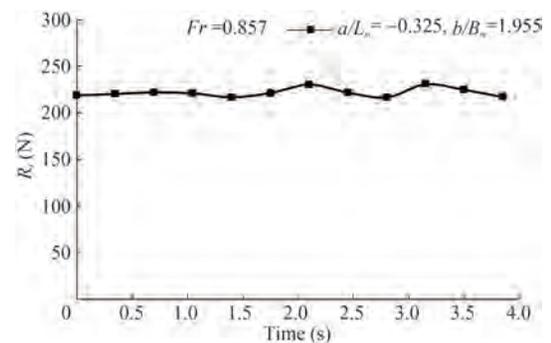


Figure 6 Time history of the total resistance of $a/L_m = -0.325$, $b/B_m = 1.955$ at $Fr = 0.857$

Based on the Froude assumption, the residuary resistance can be derived by subtracting the frictional resistance from the total resistance. Then, the coefficient of the residuary resistance can be obtained. The curves of the aftward trimaran and forward trimaran are shown in Figure 7.

From the curves in Figure 7, a notable phenomenon is observed, in which the aftward trimaran produces an unusual-

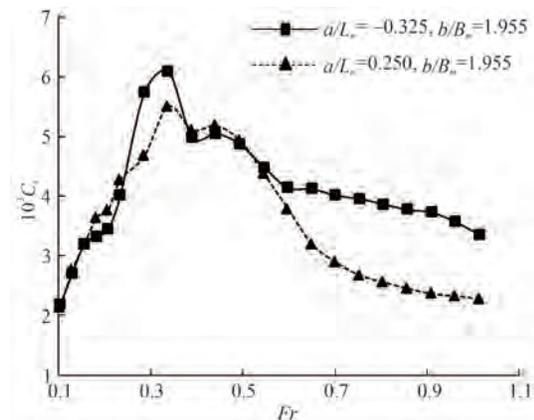
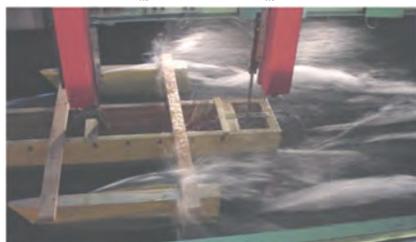


Figure 7 Coefficient of the trimaran residuary resistance

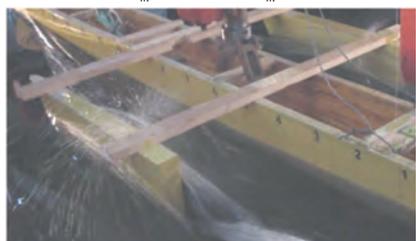
ly high resistance at high speeds ($Fr > 0.6$). To examine this, the experimental snapshots at $Fr = 0.75$ of the five configurations for the same transverse distance ($b/B_m = 1.955$) are shown in Figure 8. As shown in the pictures, the aft-ward trimaran produces strong splashes. However, the splash gradually decreases if the side hulls are moved forward. The splash even disappears for the middle trimaran and forward trimaran. Generally, a ship moving in calm wa-



(a) $a/L_m = -0.325, b/B_m = 1.955$



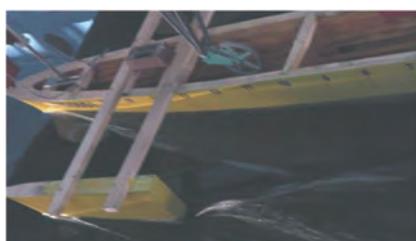
(b) $a/L_m = -0.250, b/B_m = 1.955$



(c) $a/L_m = -0.175, b/B_m = 1.955$



(d) $a/L_m = 0, b/B_m = 1.955$



(e) $a/L_m = 0.250, b/B_m = 1.955$

Figure 8 Experimental pictures in calm water at $Fr=0.75$ for Model A

ter produces Kelvin’s wave systems. If the side hulls are placed inside Kelvin’s wave systems produced by the main hull, a strong splash is produced, which results in an apparent resistance increase. This is the reason why the aft-ward trimaran produces a significantly larger resistance than the forward trimaran at a high Froude number. The relative positions of the different configurations in Kelvin’s wave systems of the main hull are shown in Figure 9. Furthermore, the two aft-ward configurations of the small lateral distance ($b/B_m = 1.117$) produce an obvious splash between the main hull and side hulls. The real Kelvin’s wave systems in the experiment are clearly shown in Figure 10.

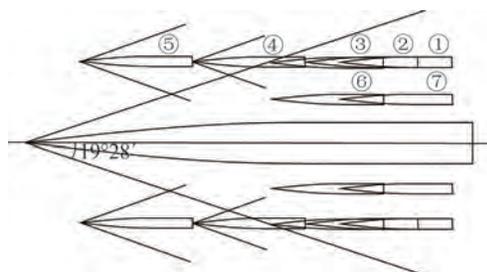


Figure 9 Kelvin’s wave systems of trimaran models



Figure 10 Picture of Kelvin’s wave systems in the experiment

To examine if the splash is dependent on sectional forms, two more models were used, which are denoted as Model B and Model C, respectively. The body plans of the two models are shown in Figure 11, and the main particulars are given in Table 3.

The same coordinates and variables as shown in Figure 12 are used. The aft-ward trimaran and forward trimaran were

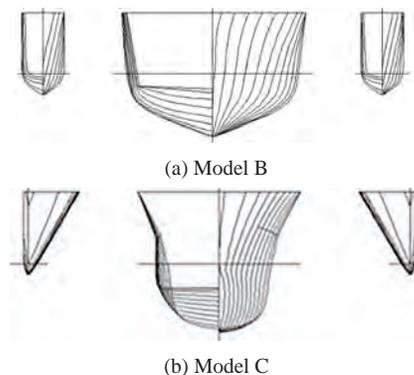


Figure 11 Body plans of Model B and Model C

Table 3 Main particulars of Model B and Model C

Items	Model B		Model C	
	Main hull	Side hulls	Main hull	Side hulls
Length of waterline (m)	4.763	2.071	4.286	2.142 9
Breadth of waterline (m)	0.458 5	0.110 4	0.247 5	0.041 2
Draft (m)	0.138 9	0.046 9	0.128 6	0.019 6
Displacement (m ³)	0.134 5	0.003 5	0.075 7	0.000 54
Wetted Surface (m ²)	2.216	0.226 3	1.572	0.096 5
Block coefficient	0.443	0.329	0.458	0.459
Prismatic coefficient	0.627	0.541	0.692	0.787

designed for the two models, which are given in Table 4. The resistance experiments were also conducted for the two models. In this test, however, a new four-component measuring instrument was used to measure the hydrodynamic performance indices.



Figure 12 Four-component measuring instrument

Table 4 Configurations of Model B and Model C

Model B		Model C	
a/L_m	b/B_m	a/L_m	b/B_m
-0.273	1.505	-0.222	1.818
0.157	1.505	0.100	1.818

The curves of the coefficients are given in Figure 13. Again, large resistance increases are observed for Models B and C at high speeds ($Fr > 0.6$). This is further verified by the observations from the pictures taken from a test run of Model B, as shown in Figure 14. Splash occurred on the aft-ward trimaran but not on the forward trimaran. The same is true for Model C. This finding strongly indicates that the splash phenomenon is a common phenomenon regardless of trimaran hull forms.

The previous analysis also reveals that the forward trimaran is advantageous in resistance performance at high speeds ($Fr > 0.6$) in calm water, due to its ability to reduce the strong splash between the main hull and side hulls. However, the optimum configuration at the low speed range ($Fr < 0.6$) may not have a forward trimaran hull form. The optimum configuration depends on speeds. Based on the experimental results of Model A, an opti-

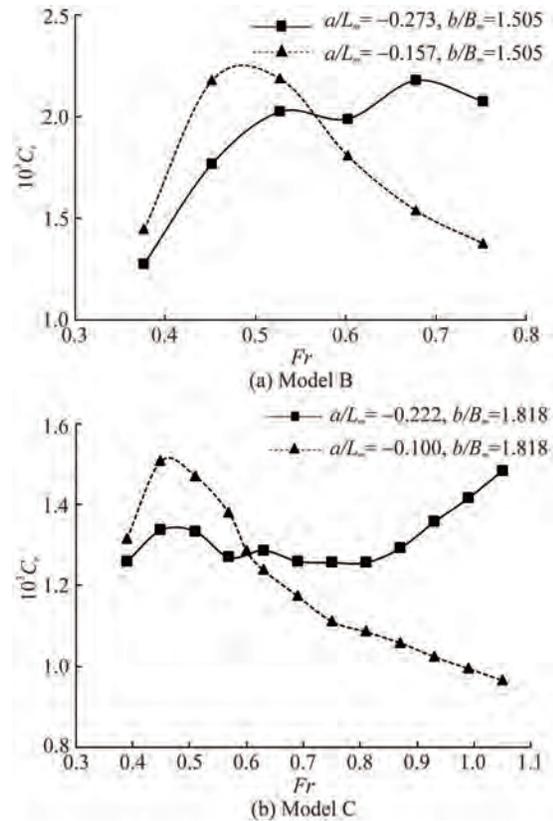


Figure 13 Coefficient of the trimaran residuary resistance of Model B and Model C

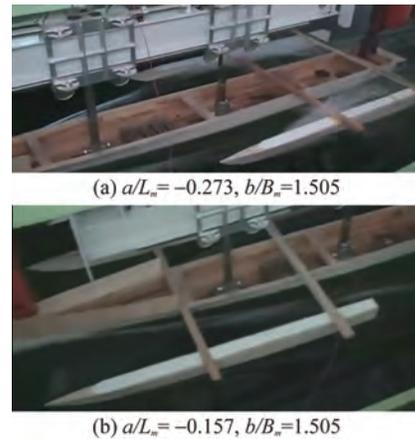


Figure 14 Experimental pictures in calm water at $Fr = 0.75$ for Model B

imum configuration spectrum for resistance in calm water was obtained, as shown in Figure 15.

3.2 Heaving at high frequencies

In Model A, the heave tests were conducted in head regular waves at four typical Froude numbers: $Fr = 0, 0.234, 0.494, \text{ and } 0.701$. The heave response amplitude operator (RAO) curves of different configurations at different Froude numbers are given in Figure 16.

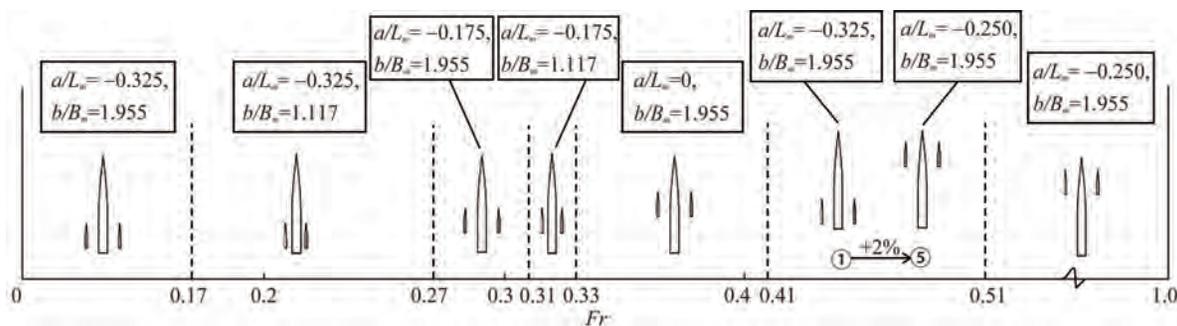


Figure 15 Spectrum of the optimum configuration of resistance in calm water

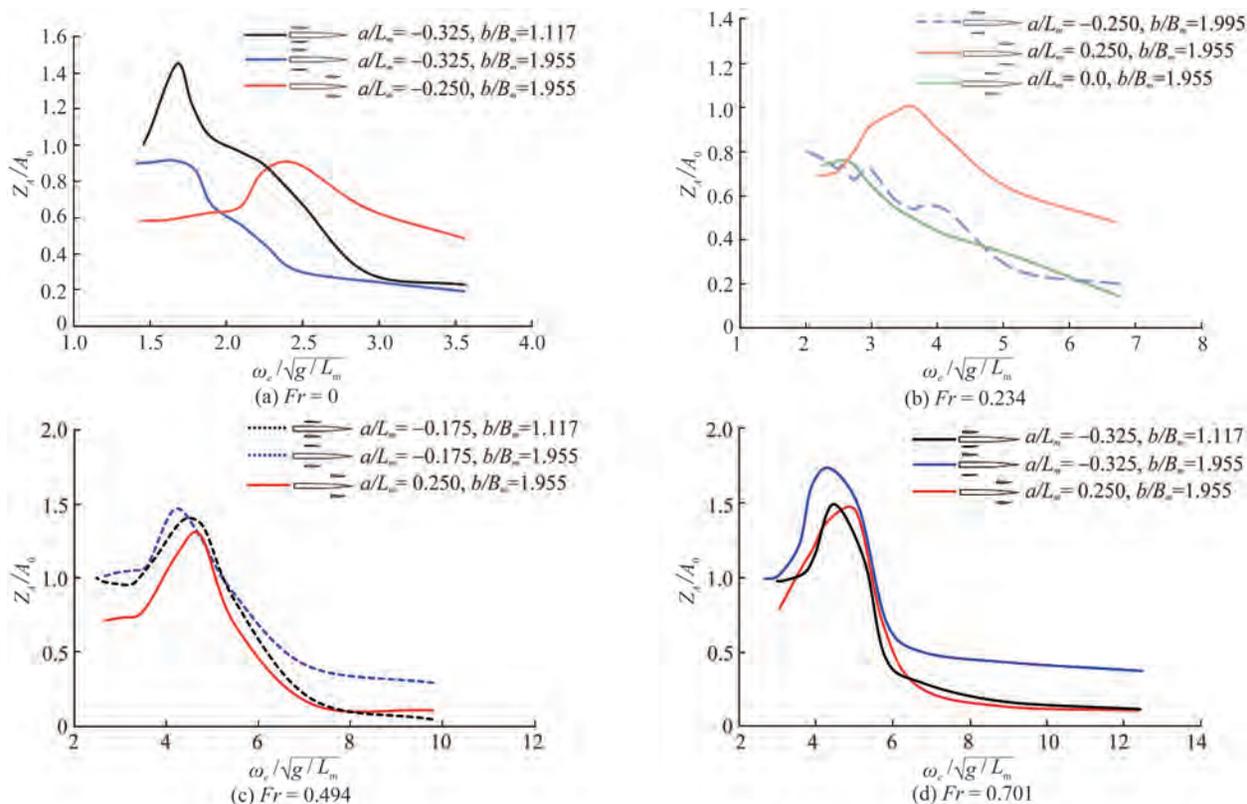


Figure 16 Heaving Response Amplitude Operators (RAOs) of different configurations for Model A

One of the interesting observations in Figure 16 is that the RAO tends to zero very slowly for certain configurations. For example, the forward trimarans in Figure 16(a) and (b) and aft-ward trimarans in Figure 16(c) and (d) exhibit a significant deviation from zero at high frequencies. This result is due to the fact that high-frequency waves, although short in length compared with those of the main hull, are comparative to the length of the side hulls, thus exciting large heaving at high frequencies.

By repeating the tests at different Froude numbers, we obtained the optimum configurations in terms of heaving amplitudes, as given in Figure 17.

3.3 Pitch at low frequencies

The pitch tests were performed in head regular waves at

four typical Froude numbers: $Fr = 0.0, 0.234, 0.494,$ and 0.701 . The pitch RAO curves for different configurations at different Froude numbers are shown in Figure 18.

Based on the ship motion theory, the pitch RAO of a mono-hulled ship in waves tends to one when the frequency is close to zero. This condition is due to the fact that the smaller the frequency, the longer the waves. If the wave is long enough, the ship will oscillate with the same amplitude as the wave. In other words, the pitch RAO should tend to one when the frequency is close to zero.

However, this case may not be true for trimaran ships. For example, in Figure 18, the pitch RAOs may not tend to one at low frequencies. In Figure 18(a) and 18(b), the red and blue lines tend to 0.8 at low frequencies. In Figure

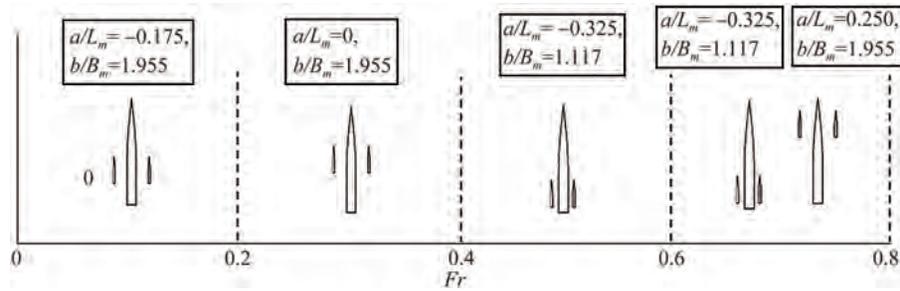


Figure 17 Spectrum of the optimum configuration for heaving in regular waves

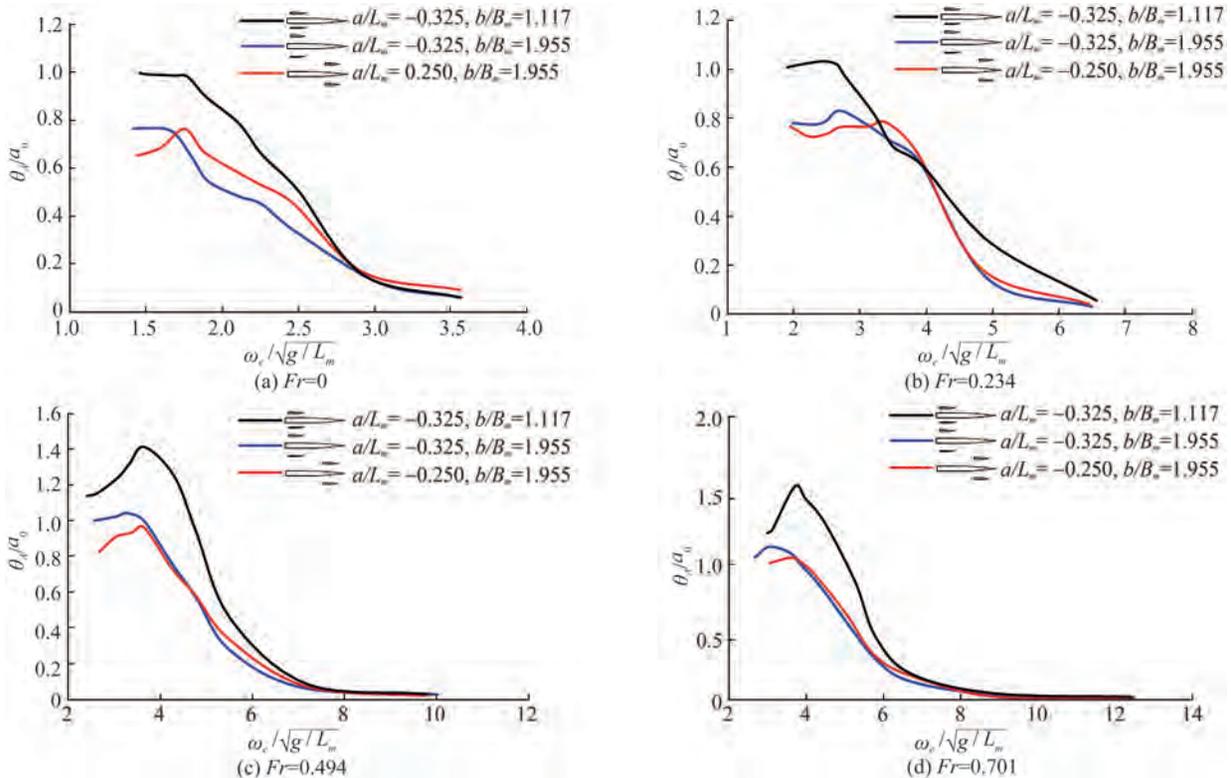


Figure 18 Pitch RAO of different configurations for Model A

18(c), the black line tends to 1.2, whereas the red line tends to 0.8. The two small side hulls provide an additional moment to the main hull. The moment lifts the ship upwards as the ship moves down and pulls the ship downwards as the ship moves up. The additional moment produced by the side hulls placed either forward or aft-ward

acts against ship motions in waves, thus reducing pitch responses.

The comparison of the curves in Figure 18 for different Froude numbers yields a spectrum of the optimum configuration for the pitch response in regular waves, as shown in Figure 19.

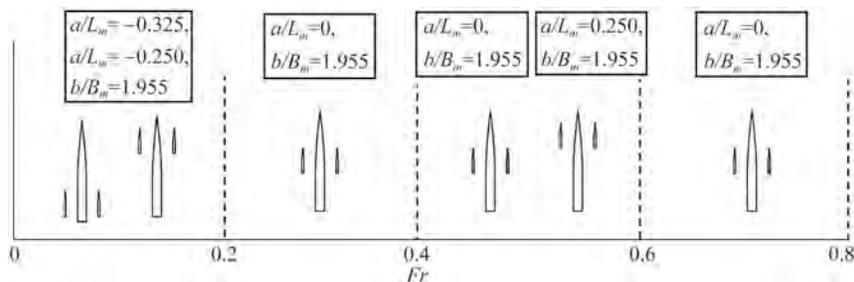


Figure 19 Spectrum of the optimum configuration for pitch in regular waves

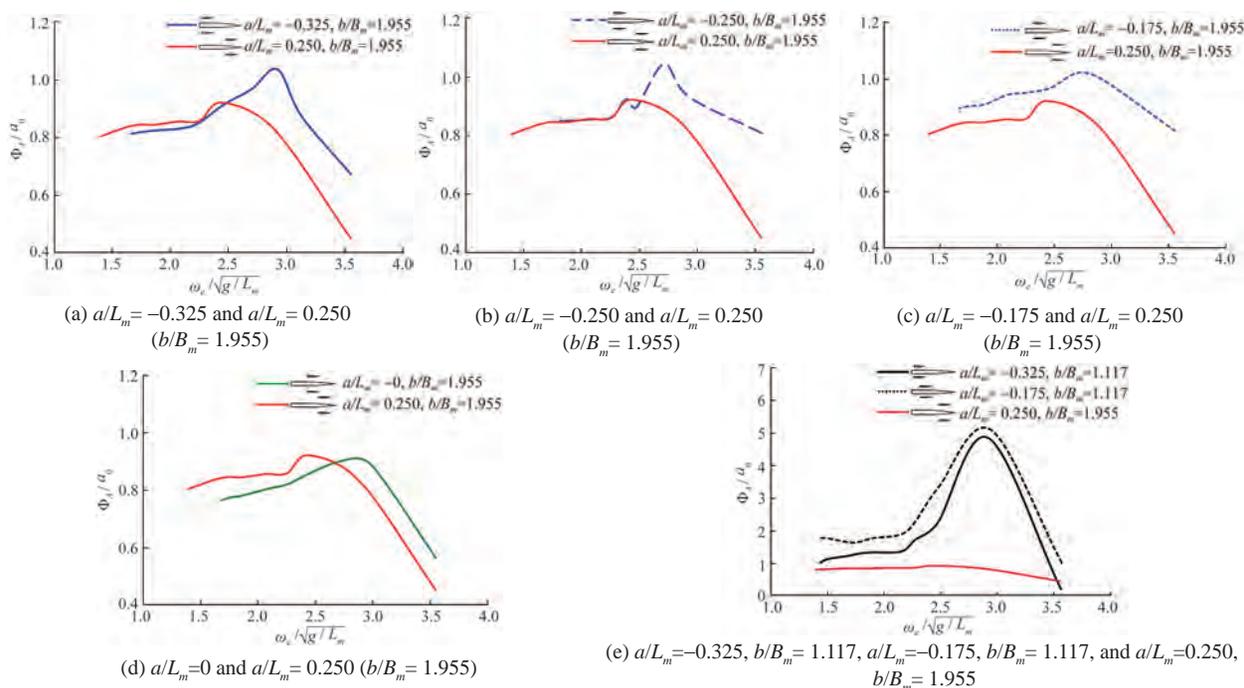


Figure 20 Roll RAO of different configurations for Model A

3.4 Roll at zero speed

The roll tests were performed in regular waves only at one Froude number of $Fr = 0$. The roll RAO curves of different configurations at $Fr = 0$ are shown in Figure 20.

The roll RAO of all the configurations did not approach 0 at high frequencies. Furthermore, the roll RAO did not approach 1 at low frequencies. At a high frequency, the wavelength is short enough for the length of the main hull but not for the side hulls. Thus, short waves may excite the side hulls to oscillate. This condition explains why the roll RAO does not tend to one at low frequencies and zero at high frequencies (Gong et al. 2021).

Meanwhile, in the figure, red lines (representing the forward trimaran configuration) are greatly lower than the blue lines (representing the aft-ward trimaran configurations), which is an interesting observation. It results from the fact that forward trimaran configurations strengthen the restoring moment at the bow, which is weaker compared with the restoring moment of the aft

part of the hull.

3.5 Resistance in regular waves

The resistance for the configurations was also tested in regular waves at three different Froude numbers: $Fr = 0.234, 0.494,$ and 0.701 . The test results are plotted in Figure 21. Different from previous results, the forward trimaran configuration is not always the best, as shown in Figure 21(b). In this case, the aft-ward trimaran configuration is better than the forward one. However, the difference is not significant, but the two configurations are close.

The aft-ward configuration of $a/L_m = -0.325, b/B_m = 1.117$ produced the smallest resistance in waves for $Fr = 0.234$ and $Fr = 0.494$. However, for $Fr = 0.701$, the forward configuration of $a/L_m = 0.250, b/B_m = 1.955$ produced the smallest resistance. A spectrum of the optimum configuration for the resistance in regular waves was obtained, as shown in Figure 22. The optimum configuration for the roll re-

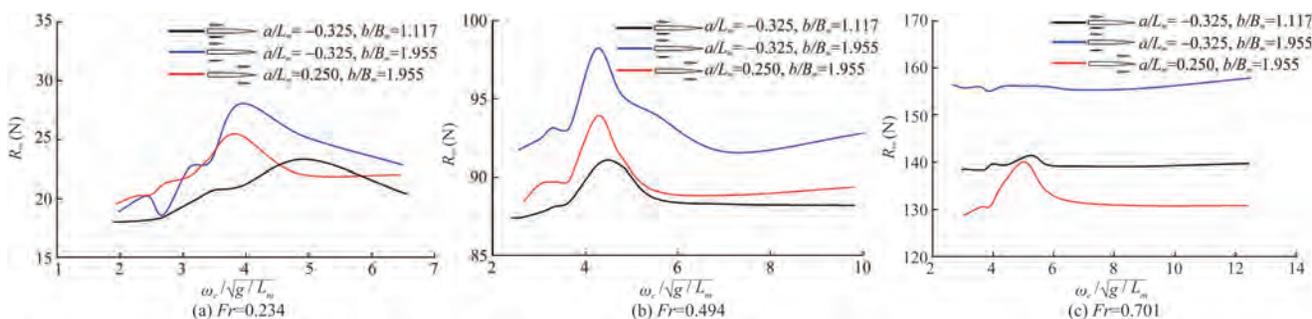


Figure 21 Resistance in waves of different configurations for Model A

sponse at $Fr = 0$ is also shown in Figure 22.

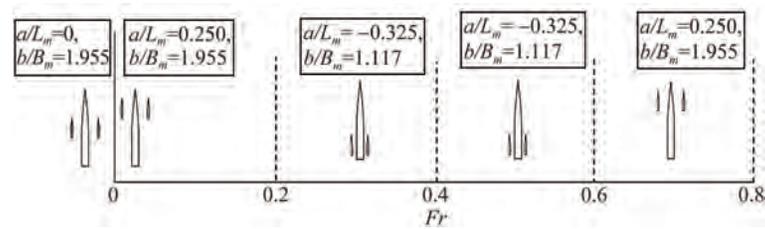


Figure 22 Spectrum of the optimum configuration for the roll and resistance in regular waves

4 Conclusions

Based on the experimental data of a series of trimaran configurations, the following conclusions can be obtained:

1) The study reveals a new resistance component of splash resistance, which is important at high speeds. The forward trimaran configuration may remove the splash resistance. For the forward trimaran, side hulls are not inside Kelvin's wave systems of the main hull, and it can avoid the splash phenomenon between the main hull and side hulls. This finding applies to all the three trimaran models tested in this study. Thus, a new configuration form (forward trimaran) is proposed.

2) The spectrum of optimum configurations for resistance in calm water versus Froude number was experimentally obtained. In addition, the experimentally obtained spectra for motions and resistance in regular waves are given.

3) Shorter waves compared with the main hull may be longer waves to the side hulls, thus exciting the side hulls to oscillate in waves. This case results in complicated behavior at high frequencies. The same is true for long waves. Therefore, sufficient consideration should be given to the arrangements of side hulls based on speed and wave conditions, which is very important at the design stage.

4) In the tests, the wooden beams connecting the three hulls interfered with the splashing. In the model tests, the wooden beams interfered with the splash. In a real ship, wooden beams are replaced with a bridge connecting the main and side hulls. Such an effect would reappear in the real case again. However, specific resistance values may be slightly different in the real and model cases. We will explore this point further in our future works.

Funding Supported by the Natural Science Foundation of China under Grant Nos. 52171294 and 52192692

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